

ICES INDEX

Manual	Index Volume
ICES STRUDL I -----	1
ICES STRUDL II Volume 1 -----	2
BRIDGE STRUDL -----	3

Index - 1

	VOL		VOL	
ABSTRACT OF STRUDL COMMANDS		CHANGE	(CONT.)	
166   1	10 - - - - -	3- 22	3	
203   2	GENERAL - - - - -	28	1	
ACTIVE, INACTIVE		GENERAL - - - - -	37	2
95   1	GENERAL - - - - -	3- 19	3	
112   2				
3- 12   3				
ADDITIONS (GENERAL)		CHECK LIST OF STRUDL COMMANDS		
28   1	- - - - -	1- 17	3	
37   2				
3- 23   3				
ANALYSIS		COMBINE		
DETERMINATE - - - - -	97   1	'ID' (EXECUTION COMMAND) - - - - -	98	1
DETERMINATE - - - - -	114   2	'ID' (EXECUTION COMMAND) - - - - -	116	2
DETERMINATE - - - - -	2- 3   3	'ID' (EXECUTION COMMAND) - - - - -	2- 5	3
PRELIMINARY - - - - -	95   1	COMMAND AND SPECIFICATION - - - - -	2- 5	3
PRELIMINARY - - - - -	101   2	COMMAND AND SPECIFICATION - - - - -	5- 14	3
PRELIMINARY - - - - -	2- 11   3	SPECIFICATION - - - - -	70	1
STIFFNESS - - - - -	97   1	SPECIFICATION - - - - -	85	2
STIFFNESS - - - - -	114   2			
STIFFNESS, PLANE TRUSS - - - - -	2- 11   3			
STIFFNESS, SPACE FRAME - - - - -	5- 11   3			
APPENDIX A		COMMENTS		
MATRIX ALGEBRA - - - - -	A- 1   3	INPUT - - - - -	3- 11	3
APPENDIX B		CONSTANTS		
STIFFNESS OR DISPLACEMENT METHOD	B- 1   3	- - - - -	64	1
		- - - - -	79	2
		MODULUS OF ELASTICITY - - - - -	2- 12	3
APPENDIX C		CONVENTIONS		
MEMBER PROPERTIES - - - - -	C- 1   3	LANGUAGE 'ID' - - - - -	10	1
		LANGUAGE 'ID' - - - - -	17	2
APPENDIX D		COORDINATES		
DATA PREPARATION AND SUBMISSION -	D- 1   3	GLOBAL - - - - -	19	1
		GLOBAL - - - - -	26	2
		GLOBAL - - - - -	1- 11	3
		JOINT - - - - -	32	1
		JOINT - - - - -	43	2
		JOINT - - - - -	1- 11	3
		JOINT - - - - -	2- 4	3
		JOINT, PLANE FRAME - - - - -	3- 11	3
		JOINT, SPACE FRAME - - - - -	5- 7	3
		LOCAL - - - - -	20	1
		LOCAL - - - - -	27	2
		LOCAL (DEFINED) - - - - -	1- 12	3
		LOCAL (PLANAR STRUCTURE) - - - - -	3- 3	3
BETA				
ANGLE, PLANE FRAME - - - - -	3- 3   3			
ANGLE, SPACE FRAME - - - - -	5- 11   3			
DEFINITION - - - - -	20   1			
DEFINITION - - - - -	28   2			
DEFINITION - - - - -	1- 13   3	DATA PREPARATION AND SUBMISSION		
		APPENDIX D - - - - -	D- 1   3	
CHANGE		DECIMAL		
ID - - - - -	26   1	OUTPUT - - - - -	104	1
ID - - - - -	75   2	OUTPUT - - - - -	123	2
ID - - - - -	2- 11   3	OUTPUT - - - - -	1- 17	3

	VOL		VOL
DELETIONS			
GENERAL	28	1	
GENERAL	37	2	
GENERAL	3- 22	3	
DEPTHES			
MEMBERS	61	1	
MEMBERS	3- 56	3	
DETERMINATE			
ANALYSIS	97	1	
ANALYSIS	114	2	
ANALYSIS	2- 2	3	
DIAGNOSTIC			
MESSAGES	145	1	
MESSAGES	161	2	
DISPLACEMENTS			
JOINT, LOAD	74	1	
JOINT, LOAD	89	2	
JOINT, LOAD	1- 4	3	
DISTORTION			
MEMBERS, LOAD	80	1	
MEMBERS, LOAD	95	2	
MEMBERS, LOAD	1- 4	3	
DISTORTIONS			
MEMBERS, LOADS	3- 8	3	
ELASTIC			
SUPPORTS	3- 22	3	
SUPPORTS	5- 47	3	
ELEMENTS			
SET	30	1	
SET	39	2	
SET	5- 6	3	
END LOADS			
MEMBERS	83	1	
MEMBERS	98	2	
MEMBERS	3- 9	3	
JOINT			
COORDINATES	32	1	
COORDINATES	43	2	
COORDINATES	2- 4	3	
COORDINATES	3- 11	3	
COORDINATES	5- 7	3	
DISPLACEMENTS, LOADS	74	1	
DISPLACEMENTS, LOADS	89	2	
DISPLACEMENTS, LOADS	1- 4	3	
LOADS	71	1	
LOADS	87	2	
LOADS	2- 5	3	
RELEASES	38	1	
RELEASES	49	2	
RELEASES	2- 4	3	
RELEASES	3- 2	3	
RELEASES	3- 11	3	
RELEASES	4- 4	3	
RELEASES	5- 10	3	
LIST			
OUTPUT	105	1	
OUTPUT	124	2	
OUTPUT	2- 5	3	
ID			
CHANGE	26	1	
CHANGE	35	2	
CHANGE	2- 11	3	
CHANGE	3- 22	3	

	VOL		VOL
<b>LOAD</b>			
COMBINATIONS, ID COMMAND - - - - -	70	1	
COMBINATIONS, ID COMMAND - - - - -	85	2	
COMBINATIONS, ID COMMAND - - - - -	2- 12	3	
COMBINATIONS, ID COMMAND - - - - -	3- 19	3	
JOINT - - - - -	71	1	
JOINT - - - - -	87	2	
JOINT - - - - -	2- 5	3	
LIST - - - - -	94	1	
LIST - - - - -	113	2	
LIST - - - - -	2- 5	3	
LIST - - - - -	2- 12	3	
LIST - - - - -	3- 12	3	
LIST - - - - -	5- 14	3	
MEMBER - - - - -	75	1	
MEMBER - - - - -	90	2	
MEMBER - - - - -	2- 11	3	
MEMBER - - - - -	3- 5	3	
MEMBER - - - - -	3- 31	3	
MEMBER END - - - - -	83	1	
MEMBER END - - - - -	98	2	
MEMBER END - - - - -	3- 9	3	
MEMBER TEMPERATURE - - - - -	78	1	
MEMBER TEMPERATURE - - - - -	93	2	
MEMBER TEMPERATURE - - - - -	3- 56	3	
<b>LOADING</b>			
GENERAL - - - - -	68	1	
GENERAL - - - - -	83	2	
GENERAL - - - - -	1- 17	3	
<b>LOCAL</b>			
COORDINATE SYSTEM - - - - -	20	1	
COORDINATE SYSTEM - - - - -	27	2	
COORDINATE SYSTEM - - - - -	1- 12	3	
<b>MATRIX ALGEBRA</b>			
APPENDIX A - - - - -	A- 1	3	
<b>MEMBER</b>			
CROSS SECTION, NONSYMMETRICAL -	3- 51	3	
DEPTHS - - - - -	61	1	
DEPTHS - - - - -	3- 56	3	
DISTORTIONS, LOAD - - - - -	80	1	
DISTORTIONS, LOAD - - - - -	95	2	
DISTORTIONS, LOAD - - - - -	1- 4	3	
DISTORTIONS, LOAD - - - - -	3- 8	3	
END LOADS - - - - -	83	1	
END LOADS - - - - -	98	2	
END LOADS - - - - -	3- 9	3	
INCIDENCES - - - - -	45	1	
INCIDENCES - - - - -	57	2	
INCIDENCES - - - - -	1- 12	3	
INCIDENCES - - - - -	2- 4	3	
INCIDENCES - - - - -	2- 12	3	
LOADS - - - - -	75	1	
LOADS - - - - -	90	2	
LOADS - - - - -	2- 11	3	
LOADS - - - - -	3- 5	3	
LOADS - - - - -	3- 31	3	
PROPERTIES - - - - -	54	1	
PROPERTIES - - - - -	71	2	
PROPERTIES - - - - -	2- 12	3	
PROPERTIES - - - - -	5- 11	3	
PROPERTIES, VARIABLE - - - - -	3- 27	3	
RELEASES - - - - -	47	1	
RELEASES - - - - -	59	2	
RELEASES - - - - -	3- 2	3	
RELEASES - - - - -	3- 29	3	
RELEASES - - - - -	4- 6	3	
RESULTS, INTERNAL - - - - -	109	1	
<b>MEMBER</b>	(CONT.)		
RESULTS, INTERNAL - - - - -	126	2	
RESULTS, INTERNAL - - - - -	3- 57	3	
TEMPERATURE LOADS - - - - -	78	1	
TEMPERATURE LOADS - - - - -	93	2	
TEMPERATURE LOADS - - - - -	3- 56	3	
<b>MEMBER PROPERTIES</b>			
APPENDIX C - - - - -	C- 1	3	
<b>MESSAGES</b>			
DIAGNOSTIC - - - - -	145	1	
DIAGNOSTIC - - - - -	161	2	
<b>MODE OF INPUT</b>			
- - - - -	28	1	
- - - - -	37	2	
<b>NONSYMMETRICAL</b>			
MEMBER CROSS SECTION - - - - -	3- 51	3	
<b>OUTPUT DECIMAL</b>			
- - - - -	104	1	
- - - - -	123	2	
- - - - -	1- 17	3	
<b>PLOTS</b>			
- - - - -	3- 42	3	
<b>PRELIMINARY ANALYSIS</b>			
- - - - -	85	1	
- - - - -	101	2	
- - - - -	2- 11	3	
<b>PRINT</b>			
OUTPUT - - - - -	101	1	
OUTPUT - - - - -	120	2	
<b>PROPERTIES</b>			
MEMBER - - - - -	54	1	
MEMBER - - - - -	71	2	
MEMBER - - - - -	2- 12	3	
MEMBER - - - - -	5- 11	3	
MEMBERS, VARIABLE - - - - -	3- 27	3	

	VOL	VOL
RELEASES	(CONT.)	
JOINT	- - - - -	49 2
JOINT	- - - - -	2- 4 3
JOINT	- - - - -	3- 2 3
JOINT	- - - - -	3- 11 3
JOINT	- - - - -	4- 4 3
JOINT	- - - - -	5- 10 3
MEMBER	- - - - -	47 1
MEMBER	- - - - -	59 2
MEMBER	- - - - -	3- 2 3
MEMBER	- - - - -	3- 29 3
MEMBER	- - - - -	4- 4 3
RESTORE	.	
	- - - - -	24 1
	- - - - -	33 2
	- - - - -	4- 3 3
	- - - - -	4- 22 3
RESULTS		
INTERNAL MEMBER	- - - - -	109 1
INTERNAL MEMBER	- - - - -	126 2
INTERNAL MEMBER	- - - - -	5- 17 3
LIST	- - - - -	105 1
LIST	- - - - -	124 2
LIST	- - - - -	2- 5 3
PRINT	- - - - -	101 1
PRINT	- - - - -	120 2
PRINT	- - - - -	2- 5 3
SAVE	.	
	- - - - -	25 1
	- - - - -	34 2
	- - - - -	4- 3 3
SECTION	.	
	- - - - -	108 1
	- - - - -	127 2
	- - - - -	5- 17 3
SET ELEMENTS	.	
	- - - - -	30 1
	- - - - -	39 2
	- - - - -	5- 6 3
SIGN CONVENTIONS	.	
	- - - - -	3- 5 3
STIFFNESS MATRIX	.	
	- - - - -	5- 4 3
STIFFNESS ANALYSIS	.	
	- - - - -	97 1
	- - - - -	114 2
	- - - - -	2- 11 3
	- - - - -	5- 11 3
STIFFNESS OR DISPLACEMENT METHOD	APPENDIX B	B- 1 3
STRUOL		
ABSTRACT OF COMMANDS	- - - - -	166 1
ABSTRACT OF COMMANDS	- - - - -	203 2
CHECK LIST OF COMMANDS	- - - - -	1- 17 3
DEFINITION	- - - - -	24 1
DEFINITION	- - - - -	33 2
TEMPERATURE LOAD		
MEMBER	- - - - -	78 1
MEMBER	- - - - -	93 2
MEMBER	- - - - -	1- 9 3
MEMBER	- - - - -	3- 8 3
THETA	.	
ANGLE	- - - - -	3- 54 3
ANGLE	- - - - -	5- 50 3
TIME	.	
	- - - - -	31 1
	- - - - -	41 2
TYPE	.	
	- - - - -	29 1
	- - - - -	38 2
	- - - - -	2- 4 3
	- - - - -	3- 10 3
	- - - - -	5- 7 3
PLANE FRAME	- - - - -	3- 1 3
PLANE GRID	- - - - -	4- 1 3
PLANE TRUSS	- - - - -	2- 1 3
SPACE FRAME	- - - - -	5- 1 3
UNITS	.	
	- - - - -	26 1
	- - - - -	35 2
	- - - - -	2- 4 3
	- - - - -	2- 12 3
	- - - - -	3- 11 3
	- - - - -	5- 7 3
USEP PROBLEM ABSTRACTS	APPENDIX E	E- 1 3